

A study on cost behaviors of binary classification measures in class-imbalanced problems

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Abstract—This work investigates into cost behaviors of binary classification measures in a background of class-imbalanced problems. Twelve performance measures are studied, such as F measure, G-means in terms of accuracy rates, and of recall and precision, balance error rate (BER), Matthews correlation coefficient (MCC), Kappa coefficient (κ), etc. A new perspective is presented for those measures by revealing their cost functions with respect to the class imbalance ratio. Basically, they are described by four types of cost functions. The functions provides a theoretical understanding why some measures are suitable for dealing with class-imbalanced problems. Based on their cost functions, we are able to conclude that G-means of accuracy rates and BER are suitable measures because they show “proper” cost behaviors in terms of “a misclassification from a small class will cause a greater cost than that from a large class”. On the contrary, F_1 measure, G-means of recall and precision, MCC and κ measures do not produce such behaviors so that they are unsuitable to serve our goal in dealing with the problems properly.

Index Terms—Binary classification, class imbalance, performance, measures, cost functions

I. INTRODUCTION

Class-imbalanced problems become more common and serious in the emergence of “Big Data” processing. The initial reason is due to a fact that useful information is generally represented by a minority class. Therefore, the class-imbalance (or skewness) ratio between a majority class over a minority one can be severely large [1]. The other reason can be appeared from utilizations of “one-versus-rest” binary classification scheme for a fast processing of multiple classes [2]. Generally, the greater the number of classes, the larger the class-imbalance ratio. When most investigations in the conventional classifications apply *accuracy* (or *error*) rate as a learning criterion, this performance measure is no more appropriate in dealing with highly-imbalanced datasets [3]. In addressing class-imbalanced problems properly, *cost-sensitive learning* is proposed in which users are required to specify the costs according to error types [4]. At the same time, the other investigations apply “proper” measures [5], or learning criteria, which do not require information about costs. Those measures, such as F -measures, AUC and G -means, are considered to be *cost-free learning* [6]. Significant progresses have been reported on using those measures [7], [8], [9], [10]. Within the classification studies, however, we consider that

two important issues below are still unclear theoretically, that is:

I. Why some of measures are successful in dealing with highly-imbalanced datasets?

II. What are the function behaviors of binary classification measures when the class-imbalance ratio increases?

The questions above form the motivation of this work. In principle, we can view that any classification measure implies cost information even one does not specify it explicitly. Taking a measure of error rate for example. When this measure is set as a learning criterion in binary classifications, a “zero-one” cost function is given to the criterion [11]. This function assigns an equal cost to both errors from two classes. Therefore, a new perspective from the cost behaviors is proposed in this study in order to answer the questions. Twelve measures are selected in this study on binary classifications. The rest of this brief paper is organized as follows. In Section II, we discuss two levels of evaluations in the selection of measures. Twelve measures in binary classifications are presented in Section III. Their cost functions are derived in Section IV. We demonstrate numerical examples in Section V. The conclusions are given in Section VI.

II. FUNCTION-BASED VS PERFORMANCE-BASED EVALUATIONS

This section will discuss measure selection in classifications. Fig. 1 shows two levels of evaluations, namely, *function-based* and *performance-based* evaluations. From an application viewpoint, the performance-based evaluation seems more common because it can provide a fast and overall picture among the candidate measures. One of typical investigations is shown by Ferri et al [12] on eighteen performance measures over thirty datasets. However, this kind of investigations generally produce the performance responses, not only to the measures, but also to the data and associated learning algorithms. Therefore, conclusions from the performance-based evaluation may be changed accordingly with the different datasets. Due to the coupling feature in the performance responses, one may fail to obtain the intrinsic properties of the measures.

We consider that the function-based evaluation is more fundamental in the measure selection. This evaluation will reveal *function* (or *property*) *differences* among the measures. Without involving any learning algorithm and noisy data, one is able to gain the intrinsic properties of measures. The properties can be various depending on the specific concerns, such as, ROC isometrics [13], statistical properties of AUC measure [14], monotonicity and error-type differentiability

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[15]. According to a specific property, one is able to see why one measure is more “proper” than the others. The findings from the function-based evaluation will be independent of the learning algorithms and datasets.

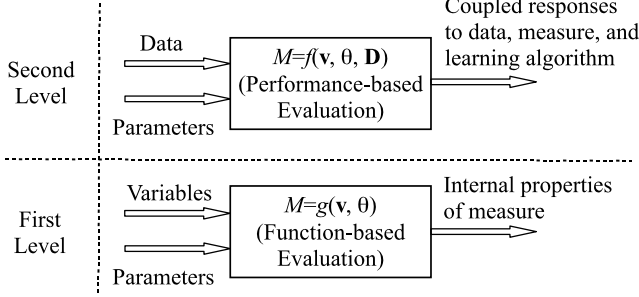


Fig. 1. Schematic diagram of two levels of evaluations in the measure selections.

In this work, we will focus on a specific property which is not well studied in the function-based evaluation. Suppose that any binary classification measure produces cost functions in an implicit form. We consider a measure to be “proper” for processing class-imbalanced problems only when it holds a “desirable” property so that “a misclassification from a small class will cause a greater cost than that from a large class” [16]. We call this property to be a “meta measure” because it describes high-level or qualitative knowledge about a specific measure. If a binary classification measure satisfies (or does not satisfy) the meta measure, we call it “proper” (or “improper”). The examination in terms of the meta-measure enables clarification of the intrinsic causes of performance differences among classification measures.

III. TWO-CLASS MEASURES

A binary classification is considered in this work, and it is given by a *confusion matrix* \mathbf{C} in a form of:

$$\mathbf{C} = \begin{bmatrix} TN & FP \\ FN & TP \end{bmatrix}, \quad (1)$$

where “TN”, “TP”, “FN”, “FP”, represent “true negative”, “true positive”, “false negative”, “false positive”, respectively. Suppose $N (= TN + TP + FN + FP)$ to be the *total number* of samples in the classification. The confusion matrix can be shown in the other form:

$$\mathbf{C} = N \begin{bmatrix} CR_1 & E_1 \\ E_2 & CR_2 \end{bmatrix}, \quad (2)$$

where CR_1 , CR_2 , E_1 , and E_2 are the *correct recognition rates* and *error rates* [16] of Class 1 and Class 2, respectively. They are defined by:

$$CR_1 = \frac{TN}{N}, \quad CR_2 = \frac{TP}{N}, \quad (3)$$

$$E_1 = \frac{FP}{N}, \quad E_2 = \frac{FN}{N}, \quad (4)$$

and form the relations to the *population rates* by:

$$p_1 = CR_1 + E_1, \quad p_2 = CR_2 + E_2. \quad (5)$$

From the non-negative terms in the confusion matrix, one can get the following constraints:

$$\begin{aligned} 0 < p_1 < 1, \quad 0 < p_2 < 1, \quad p_1 + p_2 &= 1 \\ 0 \leq E_1 \leq p_1, \quad 0 \leq E_2 \leq p_2. \end{aligned} \quad (6)$$

Twelve measures are investigated in this work. The first measure is the *total accuracy rate*:

$$A_T = \frac{TN + TP}{N} = 1 - E_1 - E_2. \quad (7)$$

In this work, we will adopt the notions of four means (Fig. 2), namely, *Arithmetic Mean*, *Geometric Mean*, *Quadratic Mean* and *Harmonic Mean*, in constructions of performance measures.

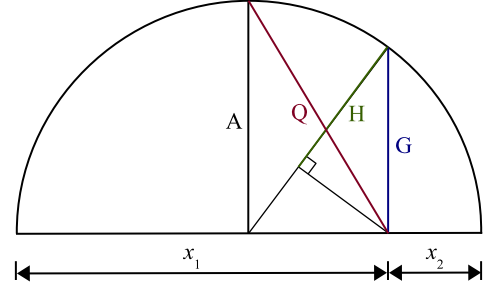


Fig. 2. Graphical interpretations of four means.

From the definitions of *precision* (P) and *recall* (R):

$$P = \frac{TP}{TP + FP} = \frac{CR_2}{CR_2 + E_1}, \quad R = \frac{CR_2}{p_2}, \quad (8)$$

one can obtain four precision-recall-based means:

$$A_{PR} = (P + R)/2. \quad (9)$$

$$G_{PR} = \sqrt{PR}. \quad (10)$$

$$Q_{PR} = \sqrt{\frac{P^2 + R^2}{2}}. \quad (11)$$

$$H_{PR} = F_1 = 2 \frac{P * R}{P + R}. \quad (12)$$

Eq. (12) shows that F_1 measure is the harmonic mean of precision and recall. More definitions are given below

$$\begin{aligned} A_1 &= TNR = \text{Specificity} = \frac{TN}{TN + FP} = \frac{CR_1}{p_1}, \\ A_2 &= TPR = \text{Sensitivity} = \frac{TP}{TP + FN} = \frac{CR_2}{p_2} = R, \end{aligned} \quad (13)$$

where the *accuracy rate of the first class* (A_1) can also be called *true negative rate* (TNR) or *specificity*; the *accuracy rate of the second class* (A_2) called *true positive rate* (TPR), *sensitivity* or *recall*. In this work, we adopt the term of *accuracy rate of the i th class* (A_i) because it is extendable if multiple-class problems are considered. The relation between the total accuracy rate and the accuracy rate of the i th class is

$$A_T = p_1 * A_1 + p_2 * A_2. \quad (14)$$

Then, four accuracy-rate-based means are formed as:

$$A_{A_i} = AUC_b = (A_1 + A_2)/2. \quad (15)$$

$$G_{A_i} = \sqrt{A_1 * A_2}. \quad (16)$$

$$Q_{A_i} = \sqrt{\frac{A_1^2 + A_2^2}{2}}. \quad (17)$$

$$H_{A_i} = 2 \frac{A_1 * A_2}{A_1 + A_2}. \quad (18)$$

In eq. (15), AUC_b is the *area under the curve* (AUC) for a single classification point in the ROC curve. AUC_b is also called *balanced accuracy* [17]. Three other measures are also received attentions. The *balance error rate* (BER) is given in a form of:

$$BER = \frac{1}{2} \left(\frac{E_1}{p_1} + \frac{E_2}{p_2} \right). \quad (19)$$

The *Matthews correlation coefficient* (MCC) is given by:

$$MCC = \frac{TP * TN - FP * FN}{\sqrt{p_1 p_2 N^2 (TN + FN)(TP + FP)}}. \quad (20)$$

The *Kappa coefficient* (κ) is given by:

$$\begin{aligned} \kappa &= \frac{Pr(a) - Pr(e)}{1 - Pr(e)}, \\ Pr(a) &= \frac{TN + TP}{N}, \\ Pr(e) &= p_1 \frac{TN + FN}{N} + p_2 \frac{TP + FP}{N}. \end{aligned} \quad (21)$$

One needs to note that the first ten measures are given in a range of $[0, 1]$, and the last two measures, MCC and κ , are within a range of $[-1, 1]$. When the four precision-recall-based measures do not take the true negative rate into account, all other measures do. Some measures above may be not well adopted in applications. We investigate them for the reason of a comparative study.

IV. COST FUNCTIONS OF MEASURES

The risk of binary classifications can be described by [11]:

$$Risk = \lambda_{11} CR_1 + \lambda_{12} E_1 + \lambda_{22} CR_2 + \lambda_{21} E_2, \quad (22)$$

where λ_{ij} is a cost term for the true class of a pattern to be i , but be misclassified as j . In the cost sensitive learning, the cost terms are generally assigned with constants [4]. However, we consider all costs in binary classifications can be described in a function form of $\lambda_{ij}(\mathbf{v})$, where \mathbf{v} is a variable vector. The size of the vector will be discussed later. We call $\lambda_{ij}(\mathbf{v})$ “*cost function*”, or “*equivalent cost*” if it is not given explicitly. In the derivation of cost functions of the given measures, we make several assumptions below:

A1. The basic information to derive the cost functions is a confusion matrix in a binary classification problem without a reject option.

A2. The population rate of the second class p_2 corresponds to the minority class, that is, $p_2 < 0.5$. Hence, p_1 corresponds to the majority class,

A3. For simplifying analysis without losing generality, we assume $\lambda_{11} = \lambda_{22} = 0$. Therefore, only $\lambda_{12}(\mathbf{v})$ and $\lambda_{21}(\mathbf{v})$ are considered, but required to be non-negative (≥ 0) for $Risk \geq 0$.

A4. When the exact cost function cannot be obtained, the Taylor approximation will be applied by keeping the linear terms, and neglecting the remaining higher-order terms. The function is then denoted by $\hat{\lambda}_{ij}(\mathbf{v})$.

When all the measures, except BER , are given in a maximum sense to the task of classifications, we need to transfer

them into the minimum sense in the form of eq. (22). This transformation should not destroy the evaluation conclusions. For example, we can find an equivalent relation between the total accuracy rate and error rates:

$$\max A_T \Leftrightarrow \min Risk(A_T) = E_1 + E_2 \quad (23)$$

where “ \max ” and “ \min ” are denoted “*maximization*” and “*minimization*” operators, respectively; the symbol “ \Leftrightarrow ” is for “*equivalency*”; and “ $Risk$ ” is the transformation operator. Using the expression of eq. (22), one can immediately obtain the equivalent costs for the accuracy measure, $\lambda_{12} = \lambda_{21} = 1$. The costs indicate constant values and no distinction between two types of errors.

However, in most cases, one fails to obtain the exact expressions on λ_{ij} . One example is given on the general form of F measure by a transformation [18]:

$$\begin{aligned} \max F_\beta &= (1 + \beta^2) \frac{PR}{\beta^2 P + R} \Leftrightarrow \\ \min Risk(F_\beta) &= \frac{E_1}{p_2 - E_2} + \frac{\beta^2 E_2}{p_2 - E_2}, \end{aligned} \quad (24)$$

from which we can only get so called “*apparent cost functions*” in a form of:

$$\lambda_{12}^A = \frac{1}{p_2 - E_2}, \quad \lambda_{21}^A = \frac{\beta^2}{p_2 - E_2}. \quad (25)$$

The term of “*apparent*” is used because the exact functions without coupling with E_i may never be obtained from the given measure. Hence, the apparent cost functions in binary classifications without a reject option can be described in a general form of:

$$\lambda_{ij}^A = \lambda_{ij}^A(E_1, E_2, p_2). \quad (26)$$

From the relations of eqs. (2)-(6), only three independent variables are used in describing the functions. One can apply the “*class imbalance* (or *skewness*) *ratio*”, $S_r = p_1/p_2$, to replace the variable p_2 for the analysis. The apparent cost functions provide users an analytical power in terms of a complete set of independent variables.

However, one is unable to realize unique representations of costs, either exact or apparent, on all measures, such as on G_{Ai} or G_{PR} . For overcoming this difficulty, we adopt a strategy of the first-order approximation, A4. Therefore, one will get a general form of $\hat{\lambda}_{ij}(p_2)$ with only a single variable for binary classifications. From the relation [4] of $\min Risk \Leftrightarrow \min a * Risk + b$, the constants a and b will be removed in the derivation of $\hat{\lambda}_{ij}(p_2)$, which will not destroy the classification conclusions.

Table I lists the all measures and their cost functions or values. Only three measures exist the exact solutions on the costs. The other measures, originally given in a form of maximization sense in classifications, need to be transformed into a minimization sense. Suppose M to be one of those measures, we adopt the following transformation:

$$Risk(M) = \frac{1}{M - M_{min}}, \quad (27)$$

where M_{min} is the minimum value of M . The transformation above is meaningful on three aspects. First, it keeps classification conclusions invariant. Second, it satisfies the assumption

TABLE I
TWELVE MEASURES AND THEIR COST FUNCTIONS.

Name of measures [Main reference]	Calculation formulas	Cost functions	When $p_2 \rightarrow 0$	Remark on cost functions
Total accuracy rate [11]	$A_T = 1 - E_1 - E_2$	$\lambda_{12} = 1$ $\lambda_{21} = 1$	$\lambda_{12} = 1$ $\lambda_{21} = 1$	Exact costs
Arithmetic mean of precision and recall [19]	$A_{PR} = \frac{P+R}{2}$	$\hat{\lambda}_{12} = \frac{1}{p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds if $E_1 > (2+\sqrt{5})E_2$
Geometric mean of precision and recall [8]	$G_{PR} = \sqrt{PR}$	$\hat{\lambda}_{12} = \frac{1}{p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds if $E_1 > (3+2\sqrt{3})E_2$
Quadratic mean of precision and recall [20]	$Q_{PR} = \sqrt{\frac{P^2+R^2}{2}}$	$\hat{\lambda}_{12} = \frac{1}{p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds if $E_1 > (\frac{5}{3} + \frac{2}{3}\sqrt{7})E_2$
Harmonic mean of precision and recall (or F_1 measure) [21]	$H_{PR} = F_1 = 2\frac{P*R}{P+R}$	$\hat{\lambda}_{12} = \frac{1}{p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds for any E_i
Arithmetic mean of accuracy rates [17]	$A_{A_i} = AUC_b = (A_1 + A_2)/2$	$\lambda_{12} = \frac{1}{1-p_2}$ $\lambda_{21} = \frac{1}{p_2}$	$\lambda_{12} = 1$ $\lambda_{21} \rightarrow \infty$	Exact functions
Geometric mean of accuracy rates [7]	$G_{A_i} = \sqrt{A_1 * A_2}$	$\hat{\lambda}_{12} = \frac{1}{1-p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} = 1$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds for any E_i
Quadratic mean of accuracy rates [22]	$Q_{A_i} = \sqrt{\frac{A_1^2 + A_2^2}{2}}$	$\hat{\lambda}_{12} = \frac{1}{1-p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} = 1$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds for any E_i
Harmonic mean of accuracy rates [23]	$H_{A_i} = 2\frac{A_1 * A_2}{A_1 + A_2}$	$\hat{\lambda}_{12} = \frac{1}{1-p_2}$ $\hat{\lambda}_{21} = \frac{1}{p_2}$	$\hat{\lambda}_{12} = 1$ $\hat{\lambda}_{21} \rightarrow \infty$	Lower bounds for any E_i
Balance error rate (BER) [24]	$BER = \frac{1}{2}(\frac{E_1}{p_1} + \frac{E_2}{p_2})$	$\lambda_{12} = \frac{1}{1-p_2}$ $\lambda_{21} = \frac{1}{p_2}$	$\lambda_{12} = 1$ $\lambda_{21} \rightarrow \infty$	Exact functions
Matthews correlation coefficient (MCC) [25]	$MCC = \frac{TP*TN-FP*FN}{\sqrt{p_1 p_2 N^2 (TN+FN)(TP+FP)}}$	$\hat{\lambda}_{12} = \frac{1}{p_2(1-p_2)}$ $\hat{\lambda}_{21} = \frac{1}{p_2(1-p_2)}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Unknown for bound features
Kappa coefficient (κ) [26]	$\kappa = \frac{TN+TP-p_1(TN+FN)-p_2(TP+FP)}{N-p_1(TN+FN)-p_2(TP+FP)}$	$\hat{\lambda}_{12} = \frac{1}{p_2(1-p_2)}$ $\hat{\lambda}_{21} = \frac{1}{p_2(1-p_2)}$	$\hat{\lambda}_{12} \rightarrow \infty$ $\hat{\lambda}_{21} \rightarrow \infty$	Unknown for bound features

of $Risk \geq 0$ because $M - M_{min} \geq 0$. Third, it can describe an infinitive risk when $M = M_{min}$.

From Table I, one can observe that the all measures investigated in this work can be classified by four types of cost functions. Fig. 3 depicts the functions with respect to a single independent variable p_2 . We will discuss the cost behaviors according to the function types first, and then the specific measures.

Type I: $\lambda_{12} = \lambda_{21} = \lambda > 0$.

The costs are positive constants with equality. The classification solutions will be independent of the constant values of costs whenever their equality relation holds. According to the meta measure, this feature suggests that the total accuracy (or error) rate measure be “improper” for dealing with class-imbalanced problems.

Type II: $\lambda_{12} = \lambda_{21} = \frac{1}{p_2}$.

Within this type of cost functions, both types of errors show the same cost behaviors with respect to the p_2 . It indicates no distinctions between two types of errors, which can be considered as an “improper” feature in class-imbalanced problems.

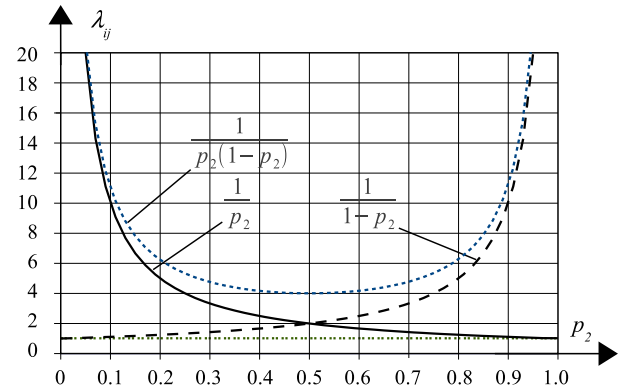


Fig. 3. Plots of cost functions with respect to p_2 .
(Black-Solid: $\lambda_{ij} = \frac{1}{p_2}$. Black-Dash: $\lambda_{ij} = \frac{1}{1-p_2}$. Blue-Dot:
 $\lambda_{ij} = \frac{1}{p_2(1-p_2)}$. Green-Dot: $\lambda_{ij} = 1$.)

Four measures from the precision-recall-based means demonstrate the same approximation expressions of $\hat{\lambda}_{12} = \hat{\lambda}_{21} = \frac{1}{p_2}$

as the lower bounds to the exact functions (Table I). However, their approximation rates are different and are not given for the reason of their tedious expressions. The feature of the lower bounds will support the conclusions about the cost behaviors of their exact functions on: λ_{12} and $\lambda_{21} \rightarrow \infty$ when $p_2 \rightarrow 0$. Another important feature is that this type of functions is *asymmetric* and imposes more costs on the positive class than on the negative class. For example, from eq. (25), F_1 measure shows smaller costs of $\lambda_{12} = \lambda_{21} = \frac{1}{1-E_2}$ if $p_1 = 0$.

Type III: $\lambda_{12} = \frac{1}{1-p_2}$, $\lambda_{21} = \frac{1}{p_2}$.

This type of cost functions shows a “*proper*” feature in processing class-imbalanced problems, because it satisfies the meta measure. One can observe that in Fig. 3, when p_2 decreases, Type II error will receive a higher cost than Type I error. Only when two classes are equal (also called “*balanced*”), two types of errors will share the same values of costs. Note that the meta measure implies such requirement. Four measures from the accuracy-rate-based means and BER measure are within this type of the functions. In a study of the cost-sensitive learning, this type of the functions can be viewed a “*rebalance*” approach [4], [5], [2]. The exact solutions of the cost functions inform that BER and A_{A_i} ($= AUC_b$) are fully equivalent in classifications. Their equivalency can also be gained from a relation of $BER = 1 - A_{A_i}$. The other three measures, G_{A_i} , Q_{A_i} and H_{A_i} , present only approximations to the exact cost functions. Their lower bound features guarantee the cost behaviors of their exact functions on $\lambda_{12} = 1$ and $\lambda_{21} \rightarrow \infty$ when $p_2 \rightarrow 0$. This type of functions shows *symmetric* cost behaviors for any class to be a minority.

Type IV: $\lambda_{12} = \lambda_{21} = \frac{1}{p_2(1-p_2)}$.

Both MCC and κ measures approximate this type of cost functions. Because the same functions are given for the two types of errors, any measure within this category will be “*improper*” for processing class-imbalanced problems. The functions are *symmetric* to either class being a minority.

From the context of class-imbalanced problems, one can further aggregate the four types of cost functions within two categories, namely, “*proper cost type*” and “*improper cost type*”. We consider only Type III cost function falls in the proper cost type, and all others belong to the improper cost type. Hence, one can reach the most important finding from the category discussions about each measure. For example, when the two geometric mean measures, G_{A_i} and G_{PR} , are applied in the class-imbalanced problems [7], [8], respectively, their intrinsic differences are not well disclosed. The present cost function study reveals their property differences about the cost response to the skewness ratio. When G_{A_i} satisfies the desirable feature on the costs, G_{PR} does not hold such feature. To our best knowledge, this theoretical finding has not been reported before.

Further finding is gained on F measure. This measure is initially proposed in the area of information retrieval [21] for an overall balance between precision and recall. Recently, F measure is adopted increasingly in the study of class-imbalanced learning [27], [28], [29]. When F measure is designed by concerning a *positive* (minority) class correctly without taking the *negative* (majority) class into account directly, it does not mean suitability in processing highly-imbalanced problems.

The cost function analysis above confirms that F measure is “*improper*” in either class to be a *minority* when its population approximates zero.

V. NUMERICAL EXAMPLES

For a better understanding of the investigated measures, we present numerical examples within two specific scenarios below.

Scenario I: Class populations are given.

Within this scenario, only two measures, BER and F_1 , are considered in the investigation for the following reasons. First, we need to demonstrate the exact cost functions graphically. When BER is qualified to this aspect, F_1 can also present the exact cost values when E_2 is known in eq. (25). Second, BER and F_1 measures are representative to be “*proper cost type*” and “*improper cost type*” respectively in cost functions. They form the *baselines* for understanding the other measures.

In the numerical examples, we assume the following data:

$$N = 10000, E_1 = 0.1, E_2 = \frac{p_2}{2}, \quad (28)$$

$$p_2 = [0.5, 0.1, 0.05, 0.01, 0.005, 0.001],$$

where p_2 is given in a vector form to present classification changes, such as from the “*balanced*” to the “*minority*” and “*rare*” stages, respectively.

Table II shows the solutions to the given data in (28) for both BER and F_1 measures. The data of BER and F_1 are calculated directly from the equations defined. The data of λ_{ij} are the exact values to each measure, respectively. One is able to confirm the correctness of λ_{ij} data through the following relations:

$$BER = \frac{1}{2}(\lambda_{12} * E_1 + \lambda_{21} * E_2). \quad (29)$$

$$\frac{1}{F_1} = 1 + \frac{1}{2}(\lambda_{12} * E_1 + \lambda_{21} * E_2). \quad (30)$$

From the data in Table II, we can depict the plots of “ λ_{ij} vs. p_2 ” for BER and F_1 measures (Fig. 4). One can observe that F_1 measure is unable to distinct the costs, but produces the same costs on the given data when p_2 decreases. Although F_β can generate different cost functions shown in (25) when $\beta \neq 1$, the infinity feature still remains in the both cost functions if $p_2 = 0$. This numerical example is sufficient to conclude that F_1 , or the other measures having the similar feature, is not suitable for processing class-imbalanced problems. On the contrary, the cost plots of BER measure confirm the theoretical findings in the previous section. Among the twelve measures investigated, the measures within Type III cost functions will exhibit the “*proper*” cost behaviors in compatible with our intuitions for solving class-imbalanced problems.

Scenario II: Gaussian distributions are given.

This scenario is designed for a class-imbalance learning. A specific set of Gaussian distributions is exactly known,

$$\mu_1 = -1, \mu_2 = 1, \sigma_1 = \sigma_2 = 1, \quad (31)$$

$$p_2 = [0.5, 0.1, 0.01, 0.001, 0.0001, 0.00001],$$

where μ_i and σ_i are the mean and standard deviation to the i th class. Five measures, A_T , BER , F_1 , G_{A_i} and G_{PR} ,

TABLE II
SOLUTION DATA OF “ λ_{ij} vs. p_2 ” FOR BER AND F_1 MEASURES FROM THE GIVEN DATA IN EQ. (28).

p_2	0.500	0.100	0.050	0.010	0.005	0.001
BER	0.350	0.306	0.303	0.301	0.300	0.300
λ_{12}	2.000	1.111	1.053	1.010	1.005	1.001
λ_{21}	2.0	10.0	20.0	100.0	200.0	1000.0
F_1	0.588	0.400	0.286	0.087	0.047	0.010
λ_{12}	4.0	20.0	40.0	200.0	400.0	2000.0
λ_{21}	4.0	20.0	40.0	200.0	400.0	2000.0

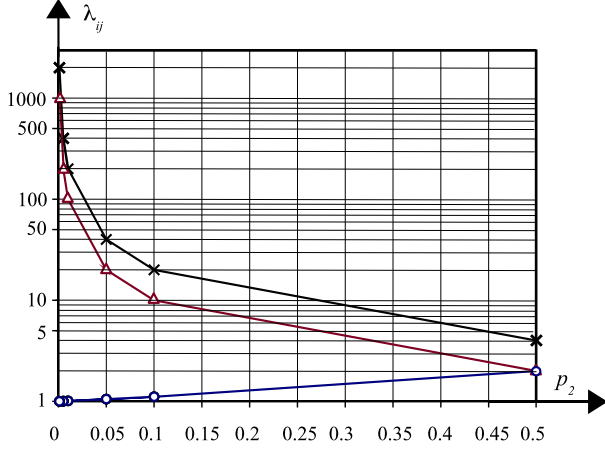


Fig. 4. Plots of “ λ_{ij} vs. p_2 ” for BER and F_1 measures on the given data in eq. (28).

(Black-Cross: $\lambda_{12} = \lambda_{21} = \frac{1}{p_2 - E_2}$ for F_1 measure.

Red-Triangle: $\lambda_{21} = \frac{1}{p_2}$, Blue-Circle: $\lambda_{12} = \frac{1}{1-p_2}$ for BER measure.)

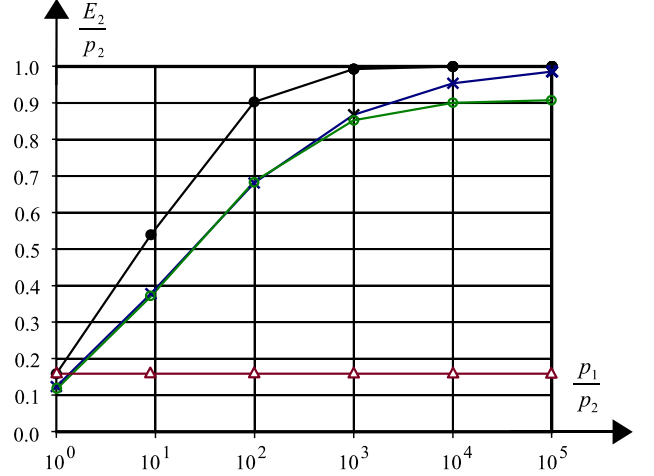


Fig. 5. Plots of “ $\frac{E_2}{p_2}$ vs. $\frac{p_1}{p_2}$ ” for five measures in Table III. (Black-Dot: from A_T measure. Blue-Cross: from F_1 measure. Green-Circle: from G_{PR} measure. Red-Triangle: from BER and G_{Ai} measures.)

are considered for a comparative study. Table III shows the *optimum* solutions to the given data in (31) from using the five measures, respectively. Based on the data in Table III, Fig. 5 depicts the plots of “ $\frac{E_2}{p_2}$ vs. $\frac{p_1}{p_2}$ ” for the measures. When the class-imbalance ratio $\frac{p_1}{p_2}$ increases, the minority class (or Class 2) is mostly misclassified for measures A_T , F_1 and G_{PR} . The value of $\frac{E_2}{p_2} = 1.0$ suggests a *complete misclassification* on all samples in Class 2. In comparison, BER and G_{Ai} measures show a small constant value of $\frac{E_2}{p_2} (= 0.1587)$, which implies a good protection on the minority class. The two measures share the same solutions for the given distribution data in eq. (31). One can show that, when $\sigma_1 \neq \sigma_2$, BER and G_{Ai} will present the different constant values. It can be further proved that all measures in Type III will produce a constant behavior shown in Fig. 5, because their decision boundaries, x_b , will be independent with the population variables.

The numerical study in this scenario provides a counterexample to confirm a general conclusion that A_T , F_1 and G_{PR} are “*improper*” measures. If “*improper*” measures are set as “*learning targets*” (or “*criteria*”) in highly-imbalanced problems, one may have a deleterious impact on classification qualities. The numerical solutions of BER and G_{Ai} support the measures to be “*proper*” only for the given datasets. However, one is unable to reach a general conclusion on the two measures via numerical studies. This scenario study is also a function-based evaluation. If using real datasets for a performance-based evaluation, inconsistency findings may be

introduced by population changes from sampling.

VI. CONCLUSIONS

This work aims at developing a theoretical insight into why some performance measures are appropriate, and some are not, for solving class-imbalanced problems. Before reviewing the existing approaches, we discuss the two levels of measure evaluations, that is, function-based evaluation and performance-based evaluation. For revealing the intrinsic properties of the measures, we consider the function-based evaluation to be necessary, and investigate one important aspect which is not well studied. This aspect is defined to be the cost behaviors of binary classification measures in terms of class-imbalance skewness ratio. We adopt a *meta measure* in [16] to examine each measure to be “*proper*” or “*improper*” in applications.

Twelve measures are studied and their cost functions, either exact or approximate, are derived. When four types of the cost functions are formed from the given measures, they are basically two kinds according to the meta measure. The “*proper*” kind includes the four means on accuracy rates and BER (equivalently including AUC_b). The other measures, i.e. A_T , the four means on precision and recall (including F_1), MCC and κ , belong to “*improper*” kind. Through the cost function analysis, one can observe their intrinsic equivalences or differences among the measures.

In apart from the measures investigated in this work, one can add other performance or meta measures for a systematic

TABLE III
OPTIMUM SOLUTIONS USING THE FIVE MEASURES RESPECTIVELY TO THE GIVEN DATA IN EQ. (31).
(THE SUBSCRIPTS "MAX" AND "MIN" STAND FOR MAXIMUM AND MINIMUM RESPECTIVELY. x_b IS A DECISION BOUNDARY.)

p_2	0.50000	0.10000	0.01000	0.00100	0.00010	0.00001
$(A_T)_{max}$	0.8413	0.9299	0.9905	0.9990	0.9999	0.9999
x_b	0.0	1.0986	2.2976	3.4534	4.6051	5.7564
E_1/p_1	1.587e-1	1.792e-2	4.876e-4	4.226e-6	1.041e-8	7.070e-12
E_2/p_2	0.1587	0.5393	0.9028	0.9929	0.9998	0.9999
$(BER)_{min}$	0.1587	0.1587	0.1587	0.1587	0.1587	0.1587
x_b	0.0	0.0	0.0	0.0	0.0	0.0
E_1/p_1	0.1587	0.1587	0.1587	0.1587	0.1587	0.1587
E_2/p_2	0.1587	0.1587	0.1587	0.1587	0.1587	0.1587
$(F_1)_{max}$	0.8443	0.6121	0.3211	0.1291	0.0420	0.0118
x_b	-1.570	0.6893	1.4705	2.1167	2.6843	3.1948
E_1/p_1	1.996e-1	4.557e-2	6.746e-3	9.145e-4	1.147e-4	1.365e-5
E_2/p_2	0.1236	0.3780	0.6810	0.8679	0.9539	0.9859
$(G_{Ai})_{max}$	0.8413	0.8413	0.8413	0.8413	0.8413	0.8413
x_b	0.0	0.0	0.0	0.0	0.0	0.0
E_1/p_1	0.1587	0.1587	0.1587	0.1587	0.1587	0.1587
E_2/p_2	0.1587	0.1587	0.1587	0.1587	0.1587	0.1587
$(G_{PR})_{max}$	0.8450	0.6123	0.3211	0.1293	0.0436	0.0139
x_b	-1.946	0.6697	1.4826	2.0481	2.2840	2.3260
E_1/p_1	2.103e-1	4.749e-2	6.519e-3	1.151e-3	5.116e-4	4.407e-5
E_2/p_2	0.1161	0.3706	0.6853	0.8527	0.9004	0.9076

study. From an application viewpoint, we understand that a final selection of measures (or learning criteria) may need to be based on an overall consideration regarding to each aspect in function-based evaluation and performance-based evaluation. The main point raised in this work confirms that "what to learn (or learning-target selection)" is the most imperative and primary issue in the study of machine learning.

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